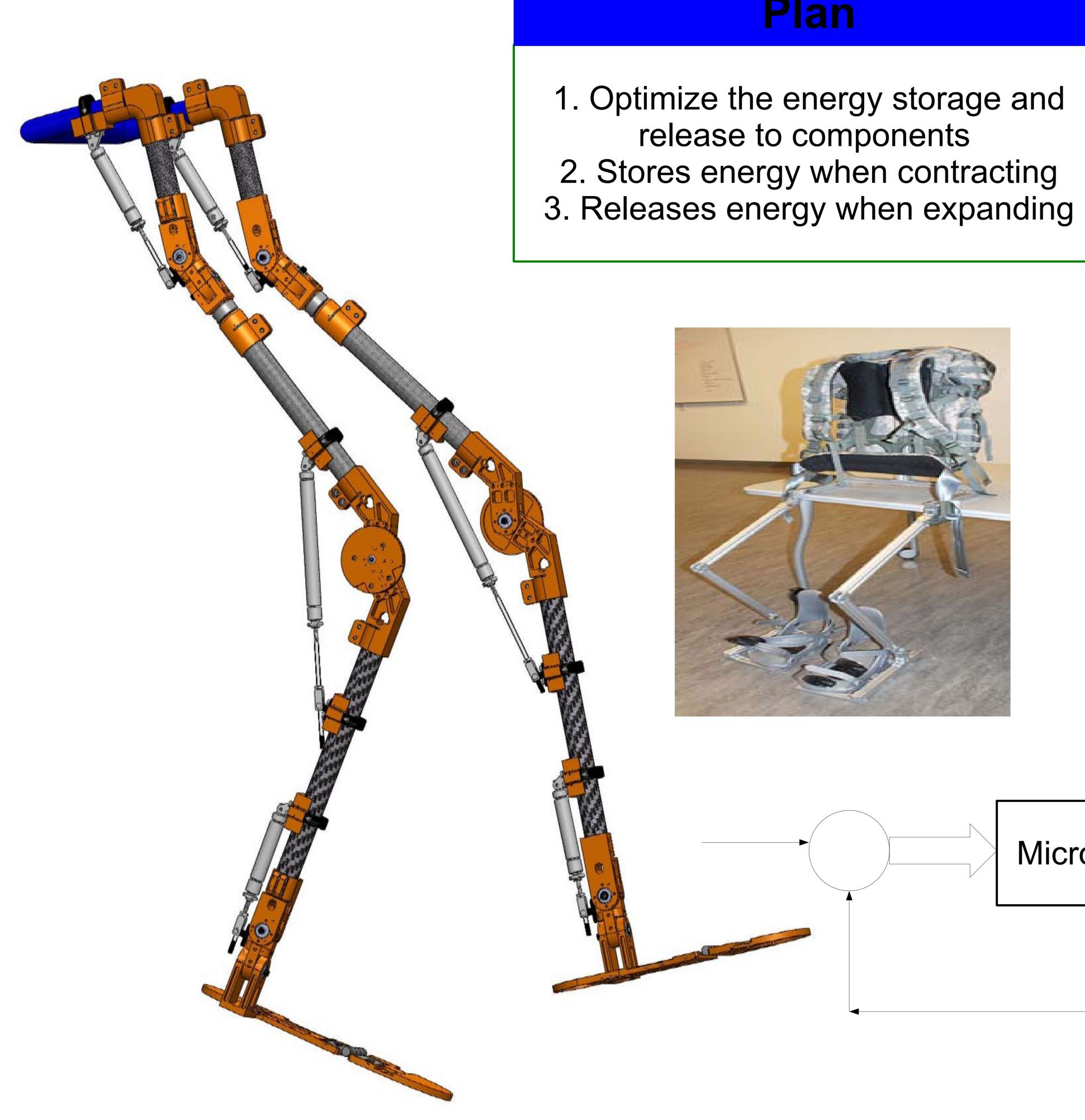




Motivation

 Assist soldiers carrying a heavy load in various terrains Reduce stress on the body Wearable Low power • Light weight



Help Us Legs: Lower Limb Exoskeleton

SURF-IT 2009, UCSC By: Tina Nguyen, UCSC Advisor: Jacob Rosen, UCSC Graduate Student: Jared Mednick, UCSC

Plan



Microcontroller

The gait cycle consist of 2 phases: . Stance: foot in contact with ground a. Heel strike to flat foot b. Foot flat through midstance c. Midstance through heel off d. Heel off to toe off a. Acceleration to midswing b. Midswing to deceleration

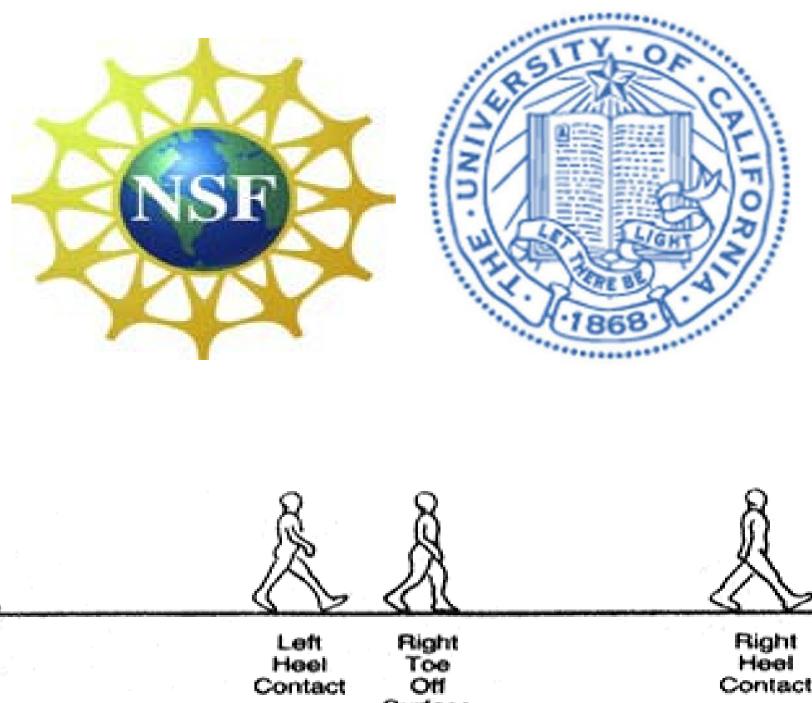
2. Swing: foot not in contact with ground

Release and store energy during gait cycle

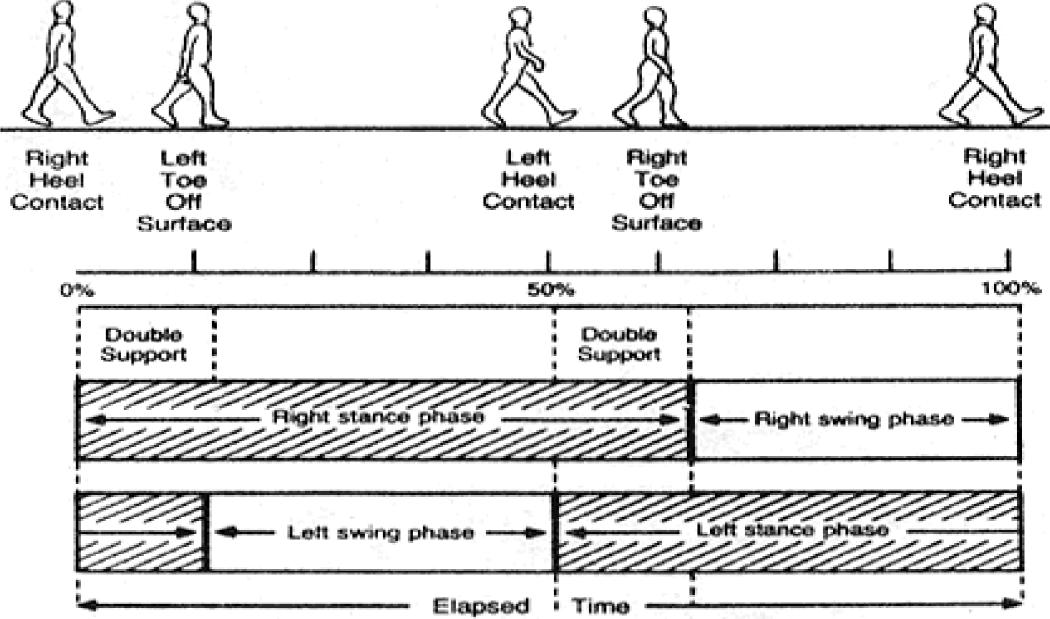


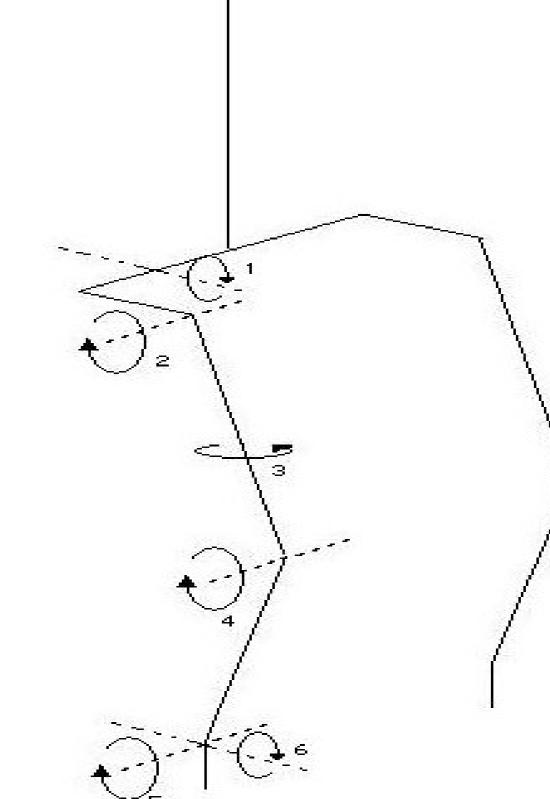
6 DOF per leg 3 Hip Joint 1 Knee Joint 2 Ankle Joint

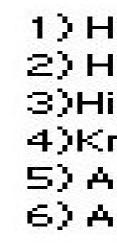




The Gait Cycle







Control System

Control Regulators Valves Sensors

1) Hip Abduction-Adduction 2) Hip Flexion-Extention 3)Hip Internal External Rotation 4)Knee Flexion-Extention

5) Ankle Plantarflexion-Dorsiflexion 6) Ankle Inversion-Enversion

